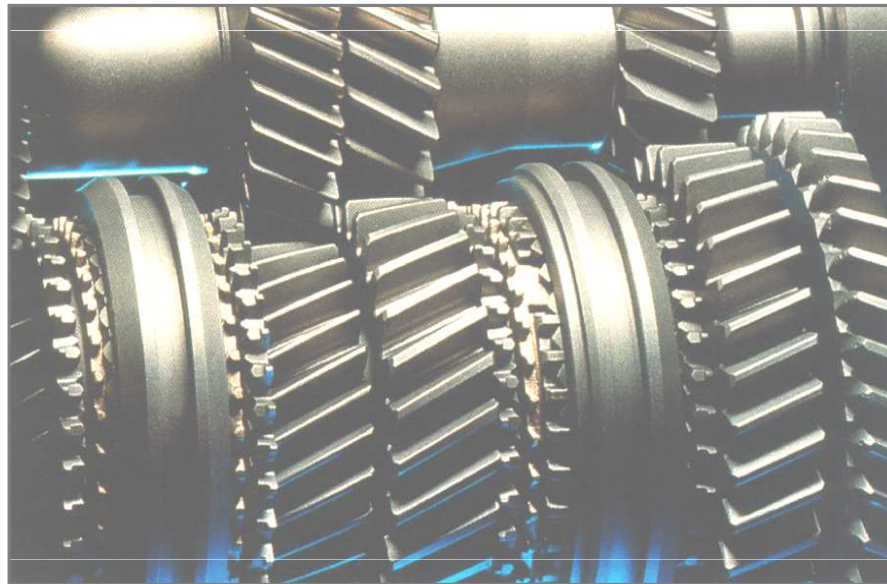


Experimental and numerical analysis of automotive gearbox rattle noise



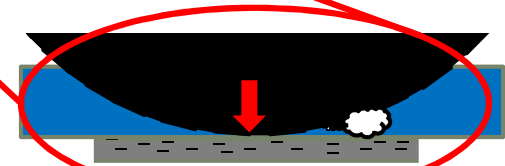
Younes KADMIRI
Emmanuel RIGAUD, Joël PERRET-LIAUDET

Introduction

Improving acoustic confort

External noise sources:

- Aerodynamic
- Pneumatic



Introduction



Numerical model



Idle gear dynamics



Housing vibration



Conclusion



Introduction

Improving acoustic confort

External noise sources:

- Aerodynamic
- Pneumatic

Internal noise sources:

- Engine
- Gearbox
(gear whine, rattle noise)



Engine



Gearbox

Introduction



Numerical model



Idle gear dynamics



Housing vibration

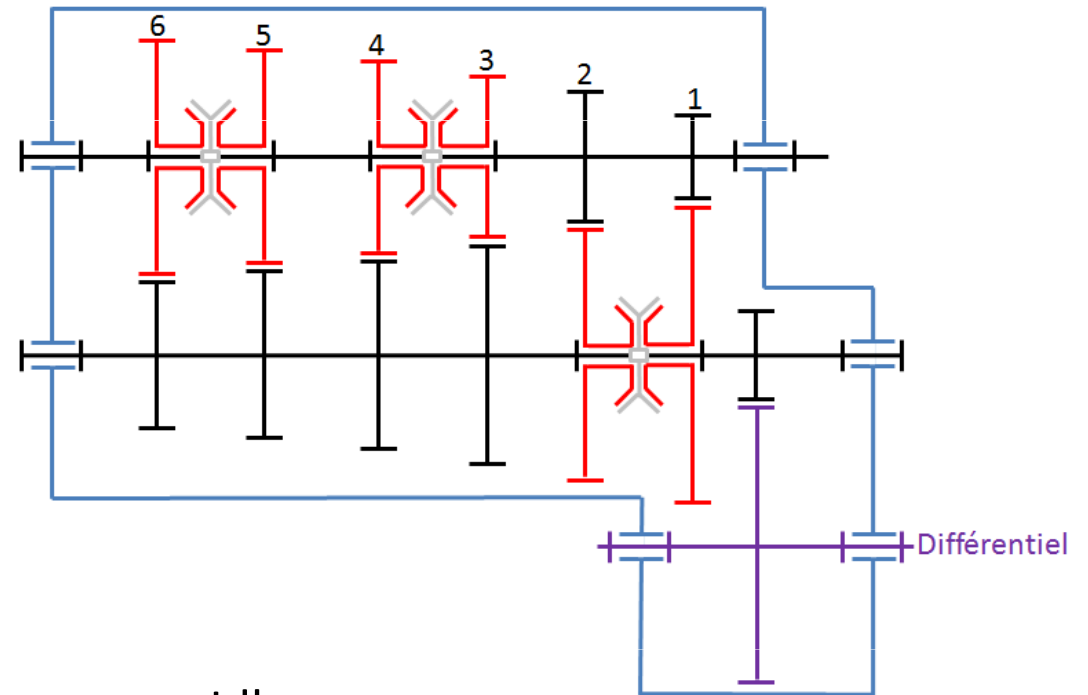


Conclusion



Introduction

Kinematic scheme of TL4 gearbox



- Idle gears
- Driving gears and shafts
- Synchronizing system
- Differential
- Housing

Introduction

Numerical model

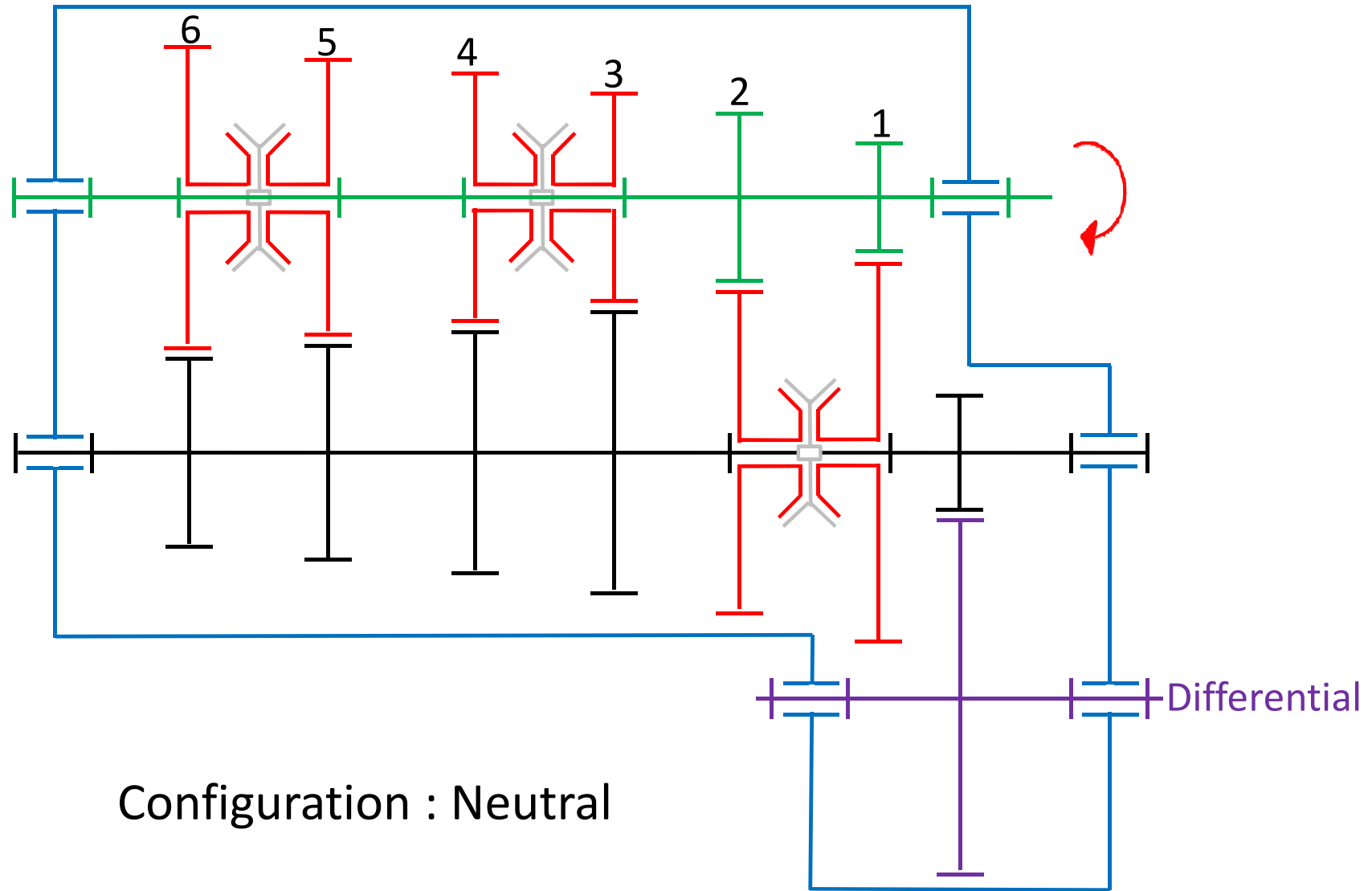
Idle gear dynamics

Housing vibration

Conclusion



Introduction



Configuration : Neutral

Introduction

Numerical model

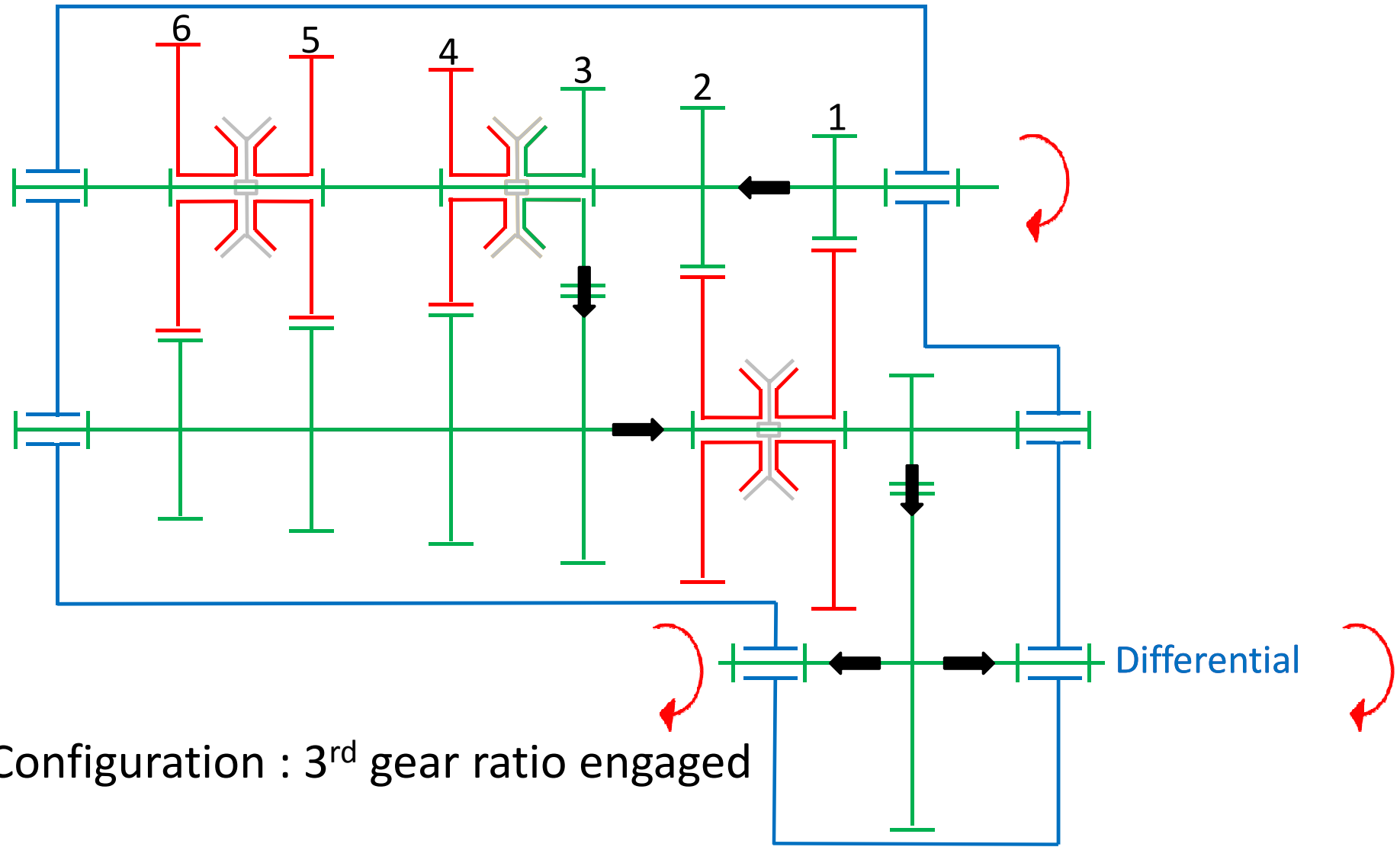
Idle gear dynamics

Housing vibration

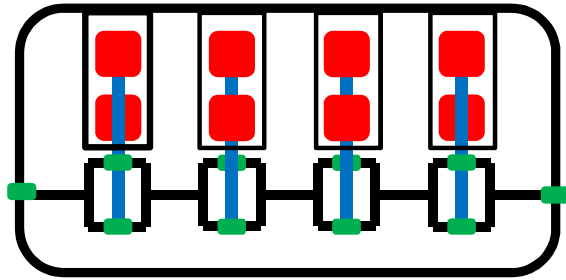
Conclusion



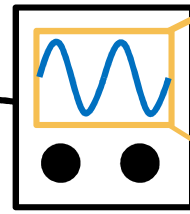
Introduction



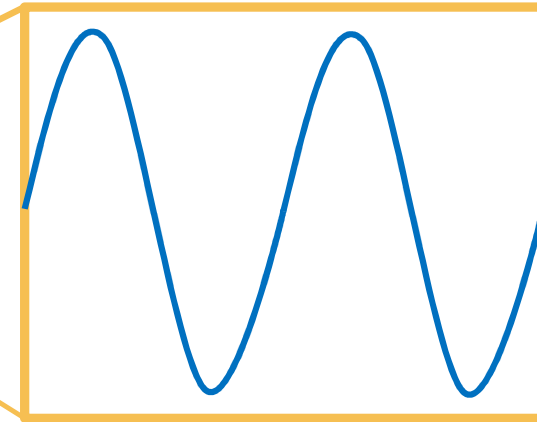
Introduction



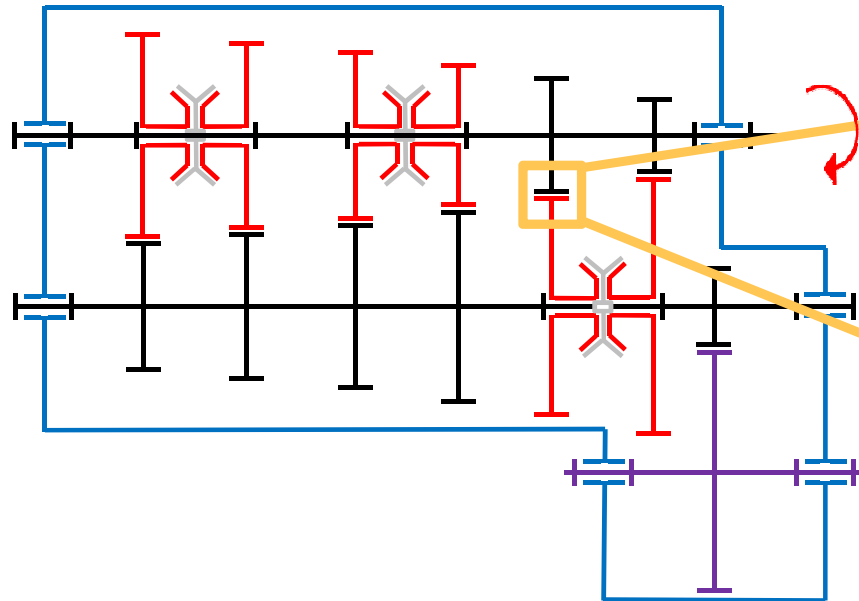
Four-cylinder four stroke engine



Velocity



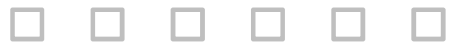
Time



Introduction



Numerical model



Idle gear dynamics

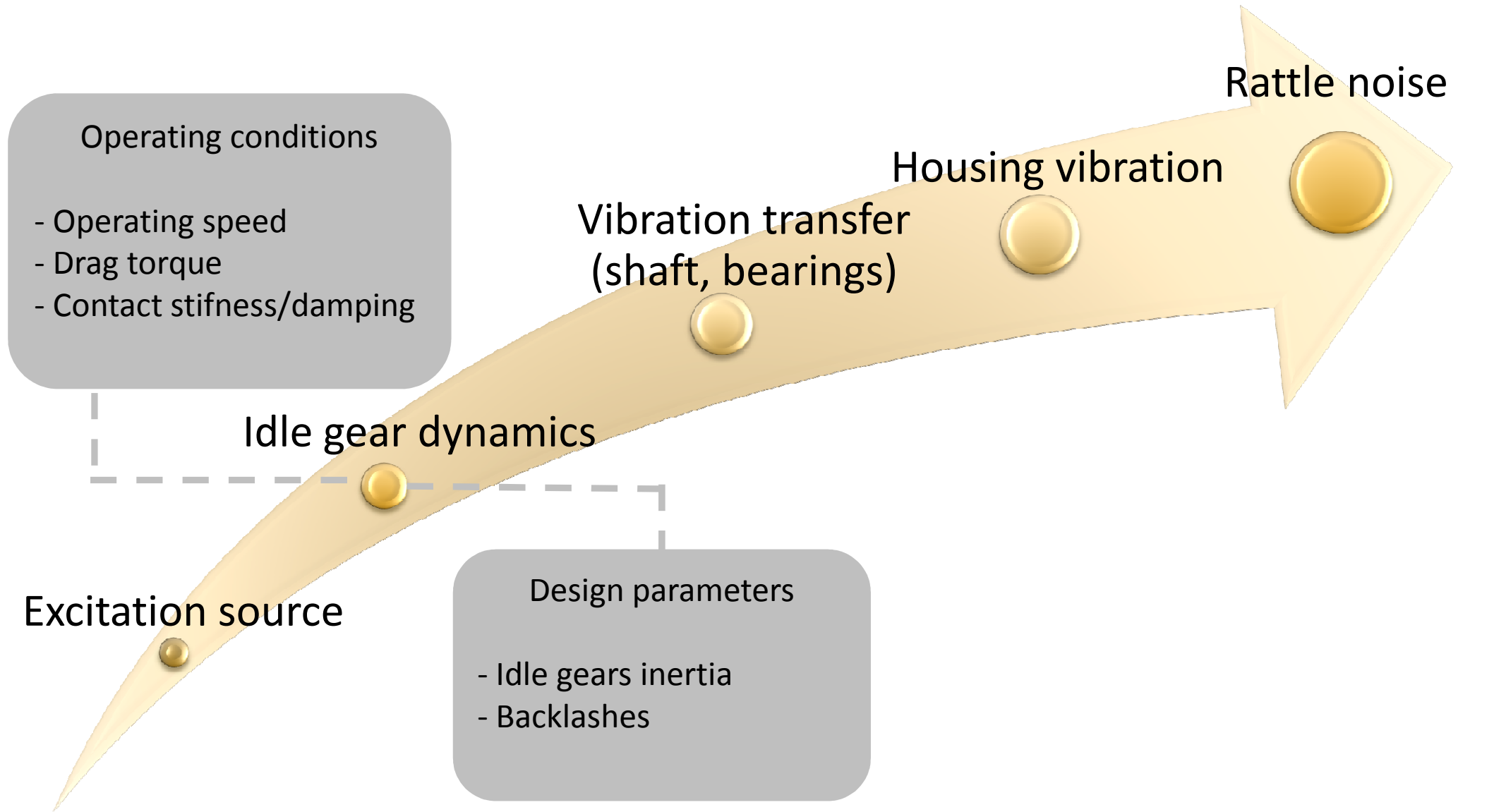
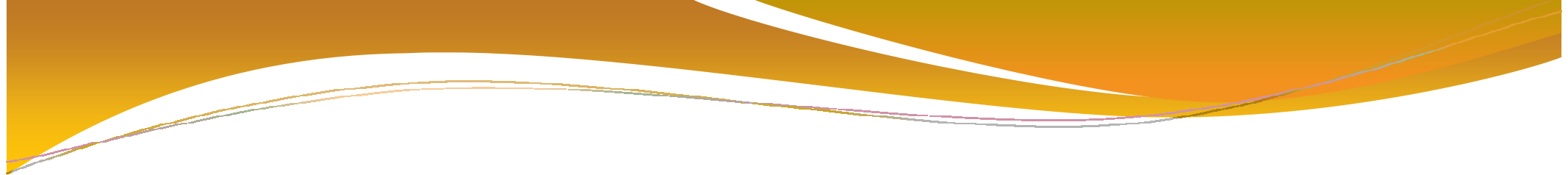


Housing vibration

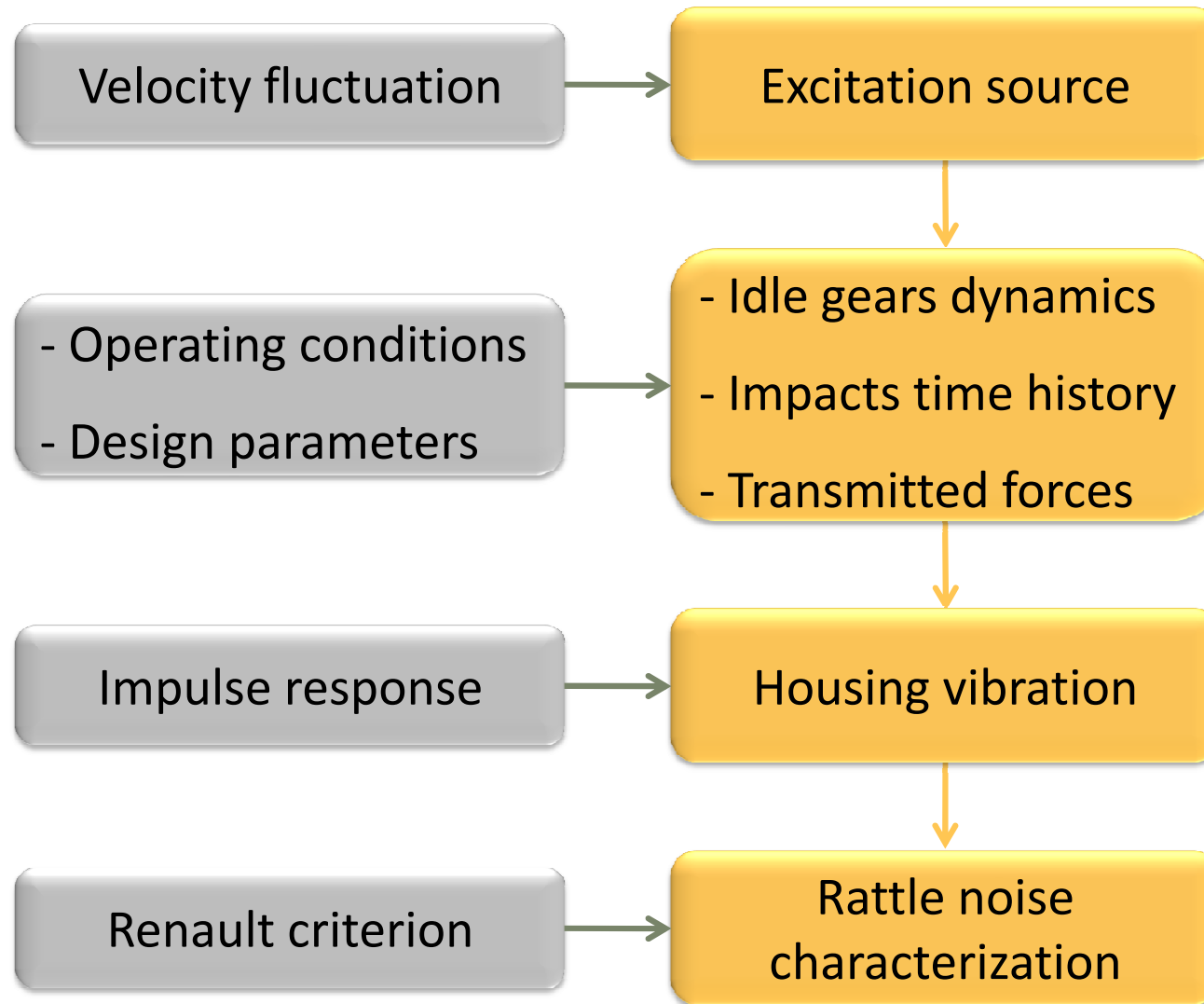


Conclusion

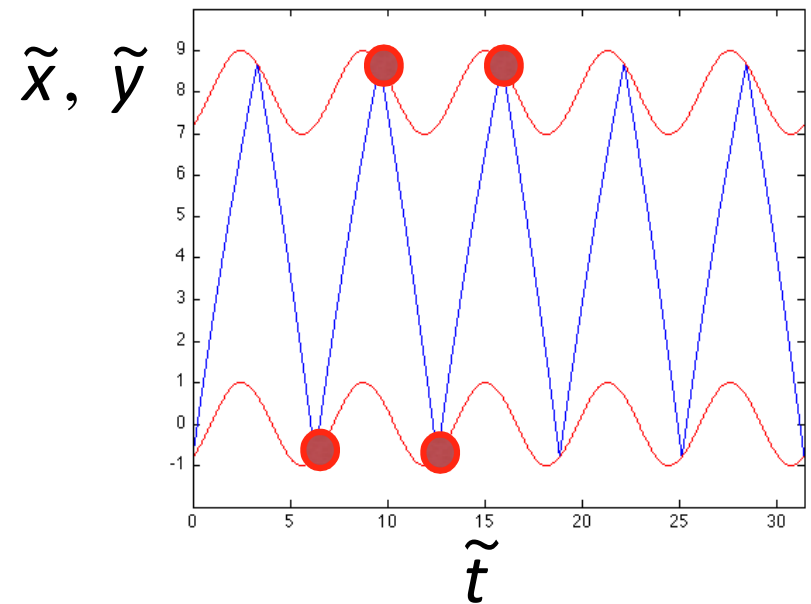
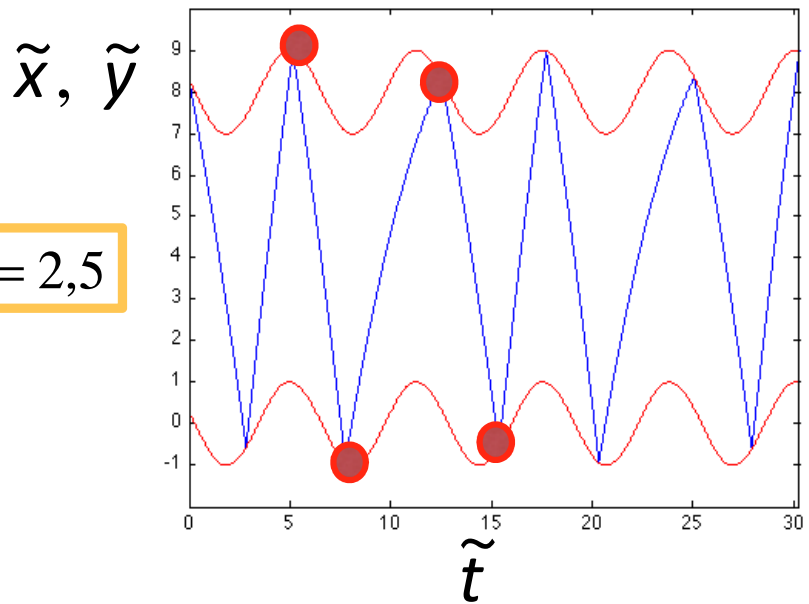
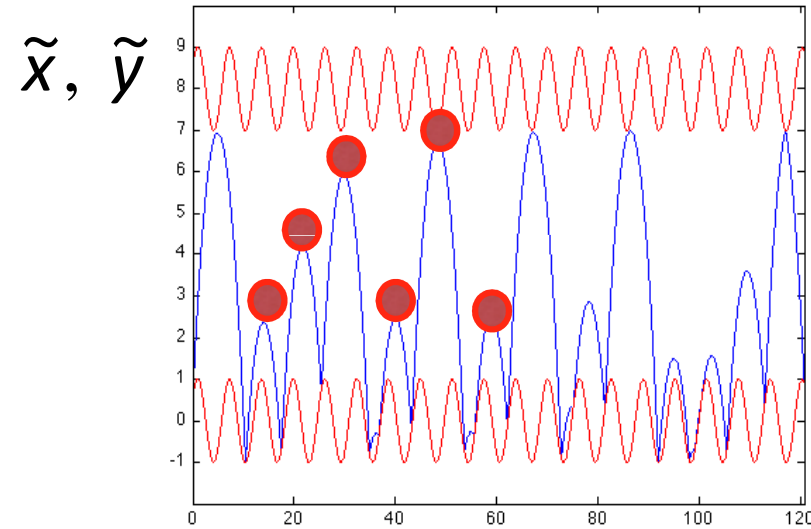
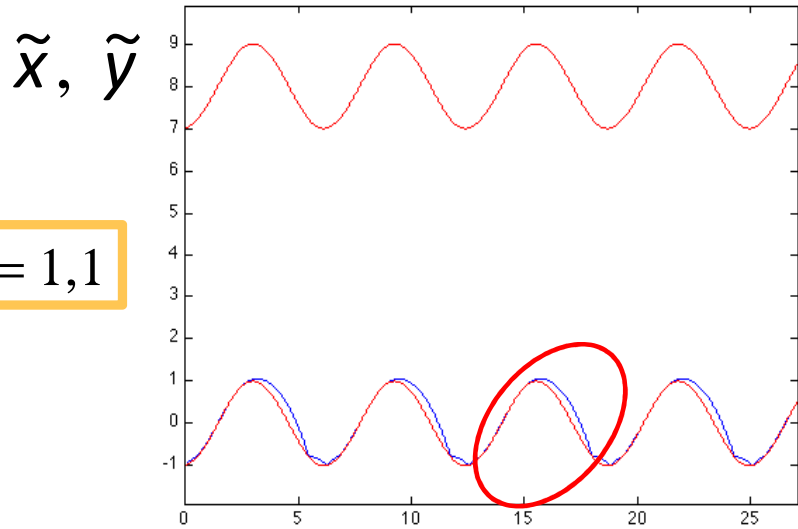




Numerical model



Time responses for $\tilde{j} = 8, r = 0.85$



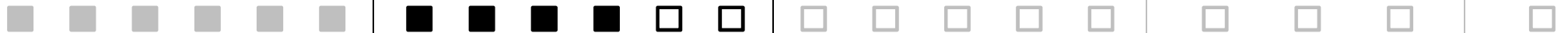
Introduction

Numerical model

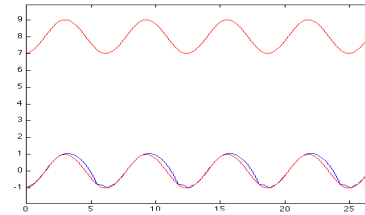
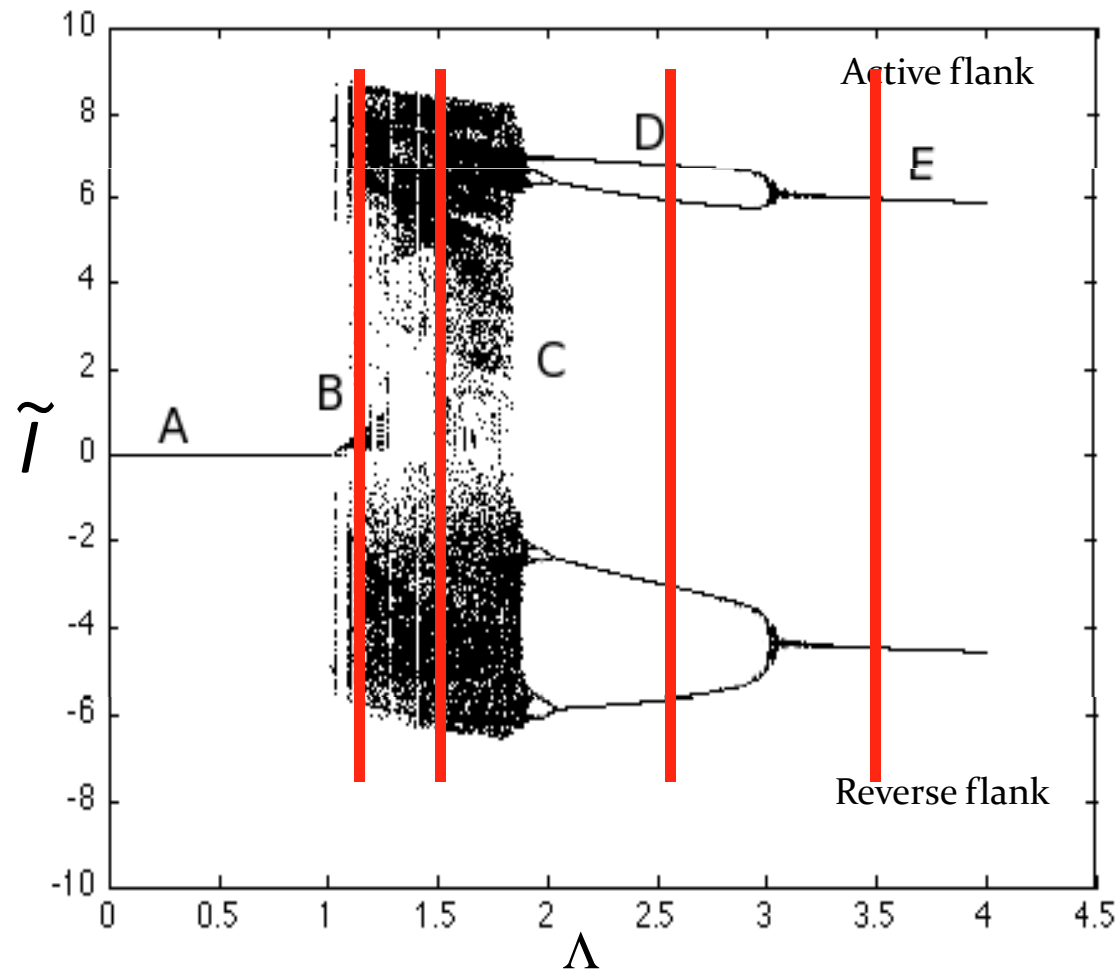
Idle gear dynamics

Housing vibration

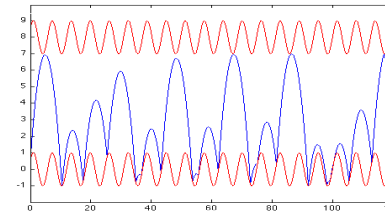
Conclusion



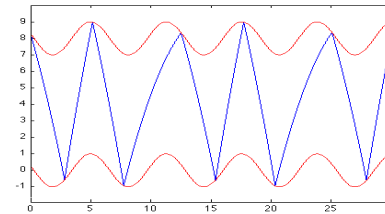
Impulses diagram



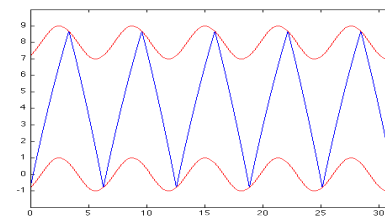
B: rebounds and contact intermittency



C: chaotic response



D: 2T 2 impacts response



E: 1T 2 impacts response

Introduction



Numerical model



Idle gear dynamics



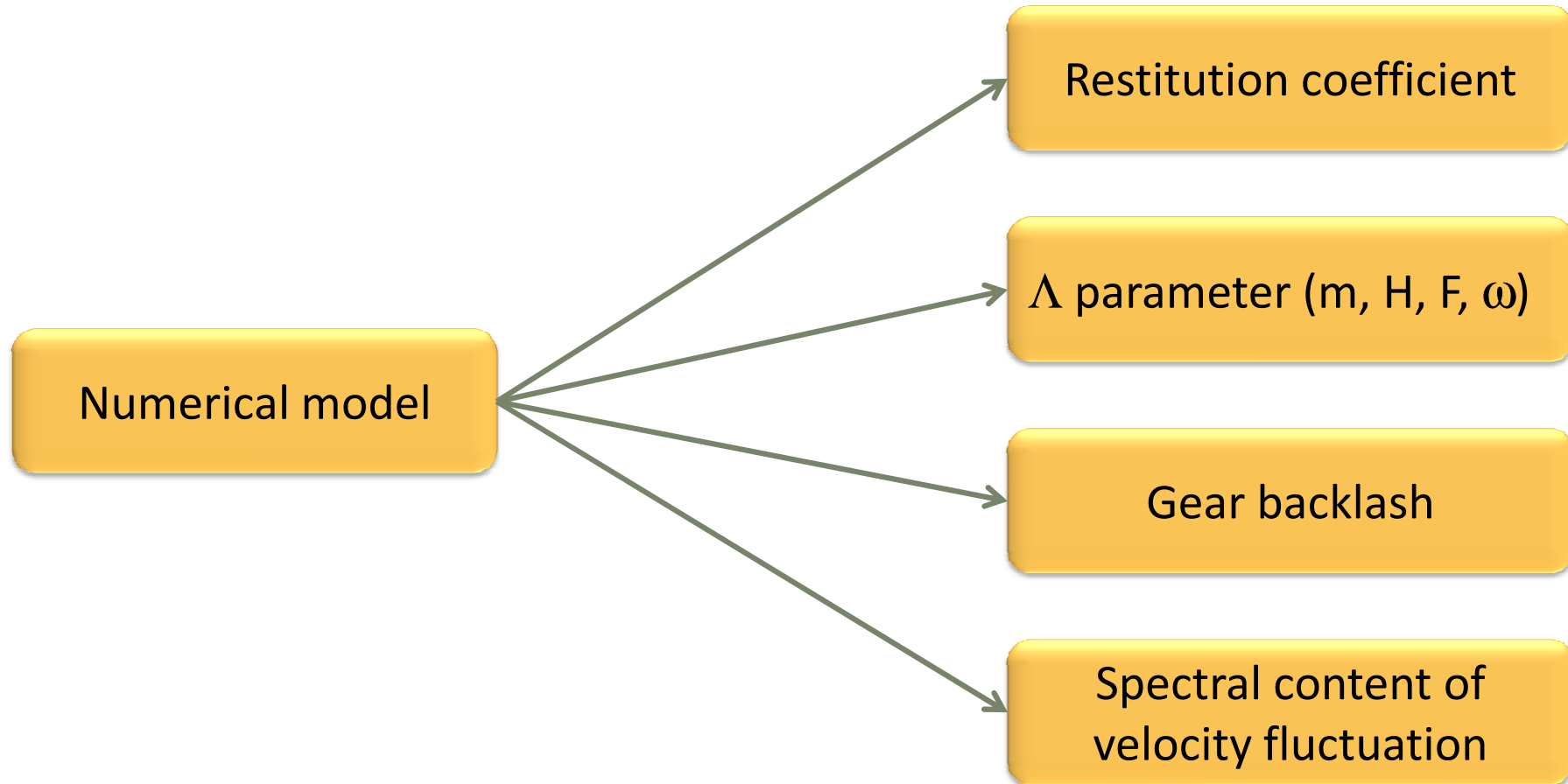
Housing vibration



Conclusion



Conclusion

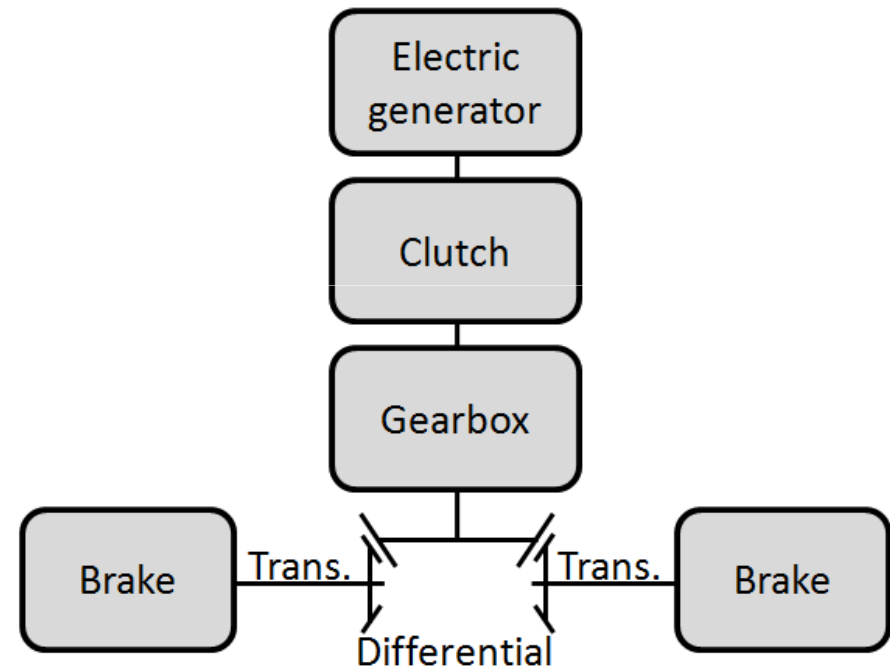


Measuring these parameters is necessary

Test bench (BACY)

Experiments performed :

- Key parameters measurement (restitution coeff., drag torque, ...)
- Idle gear dynamics measurement
- Housing vibration measurement
- Radiated noise measurement.



Introduction

Numerical model

Idle gear dynamics

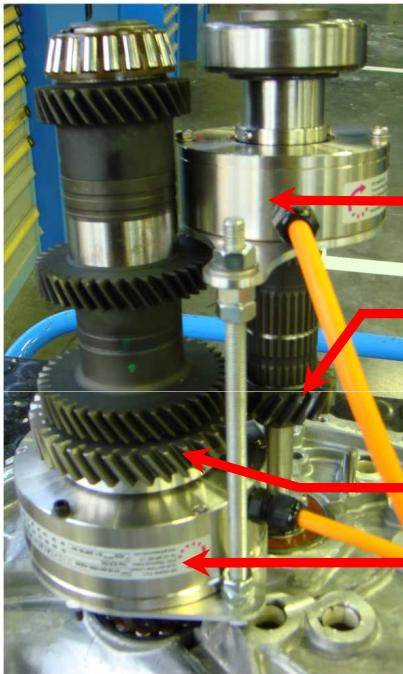
Housing vibration

Conclusion



Gearbox instrumentation

- Weak dimensions
- Small gear backlash = 0.1 mm
- Idle gear and supporting shaft are independent
- Severe operating conditions (high Ω , oil churning, high T, ...)



Optical encoder on driving gear

Driving gear

Idle gear

Optical encoder on idle gear



Configuration : 2nd gear ratio

Configuration : 2nd, 3rd and 4th gear ratio

Introduction

Numerical model

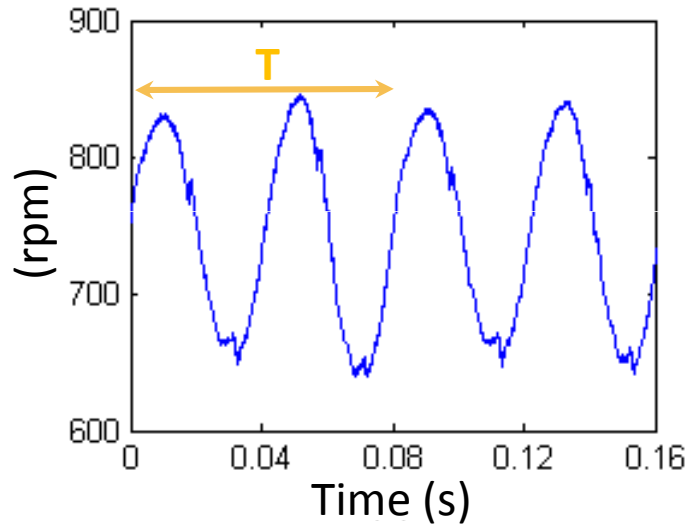
Idle gear dynamics

Housing vibration

Conclusion



Idle gear dynamics



$\Omega = 750$ rpm et $A = 50$ rpm
Neutral

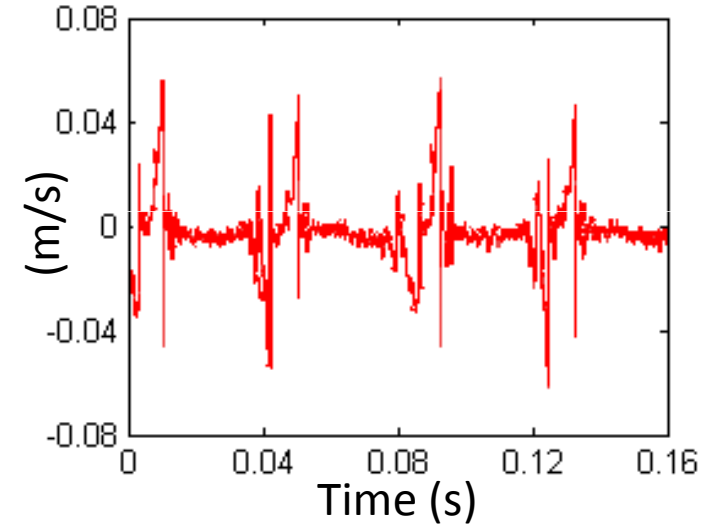
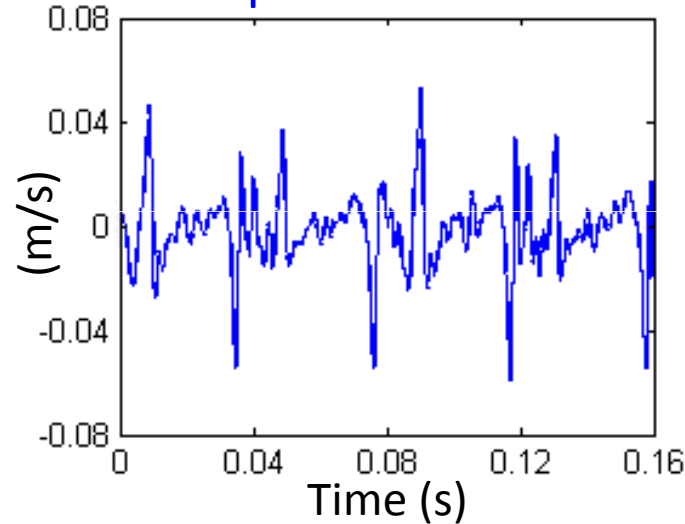
$$\Phi_i = t_i [T]$$

Φ : phase (s)

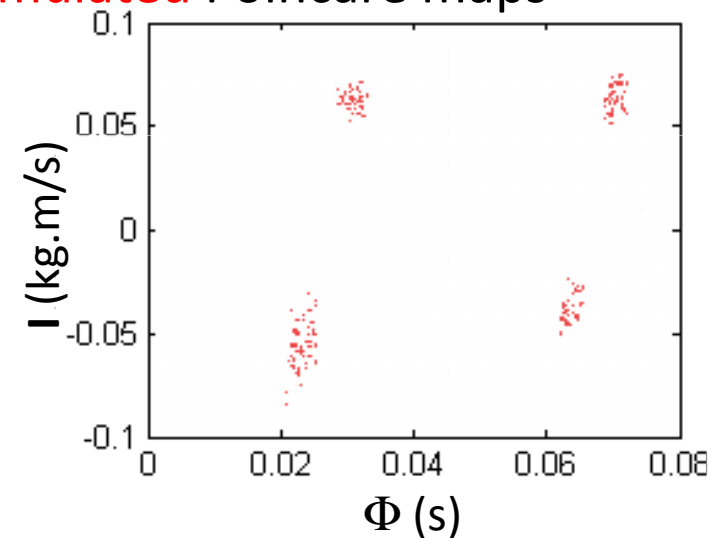
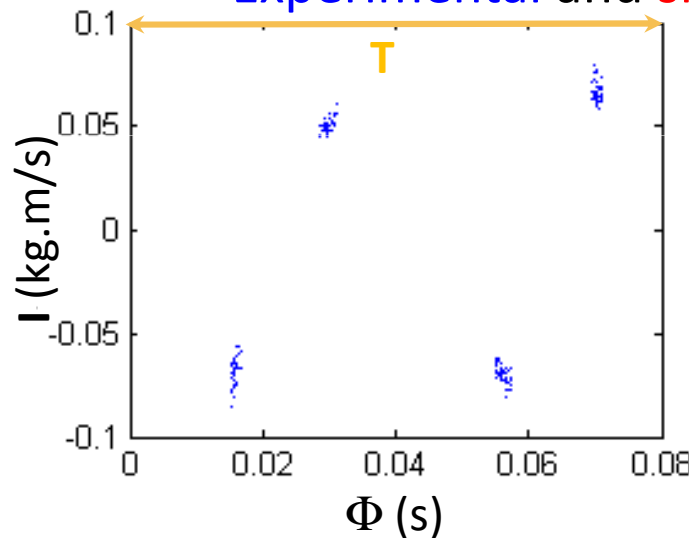
t_i : Impact time

T : period

Experimental and simulated relative velocities



Experimental and simulated Poincaré maps



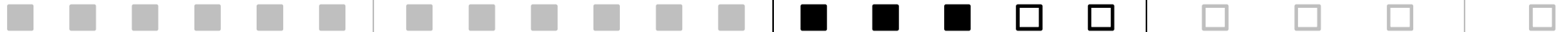
Introduction

Numerical model

Idle gear dynamics

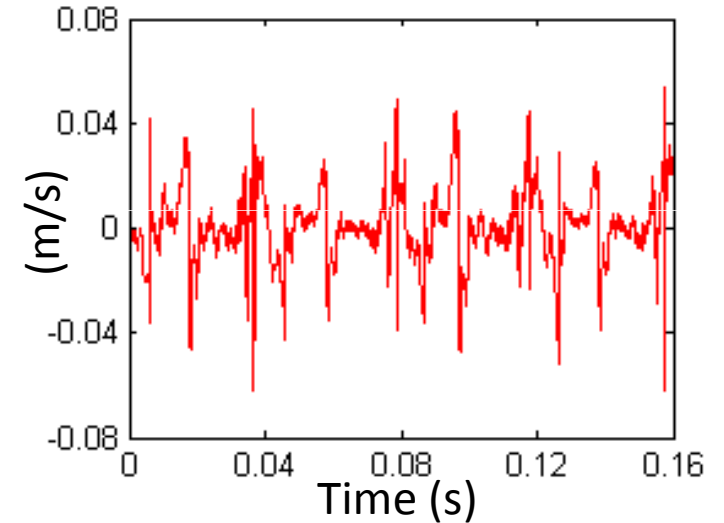
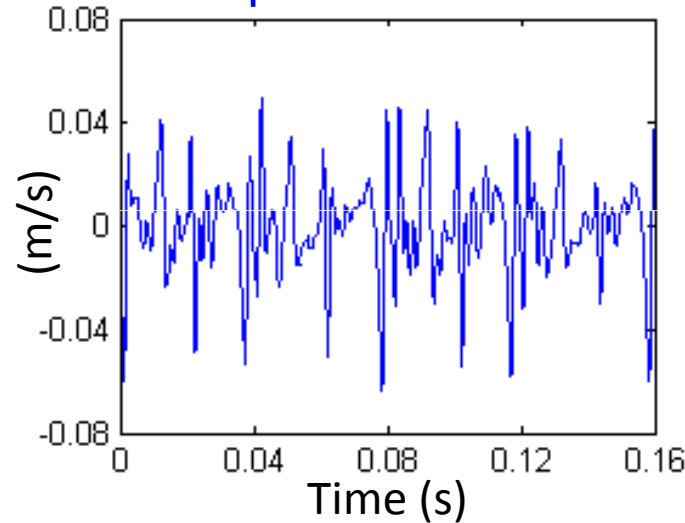
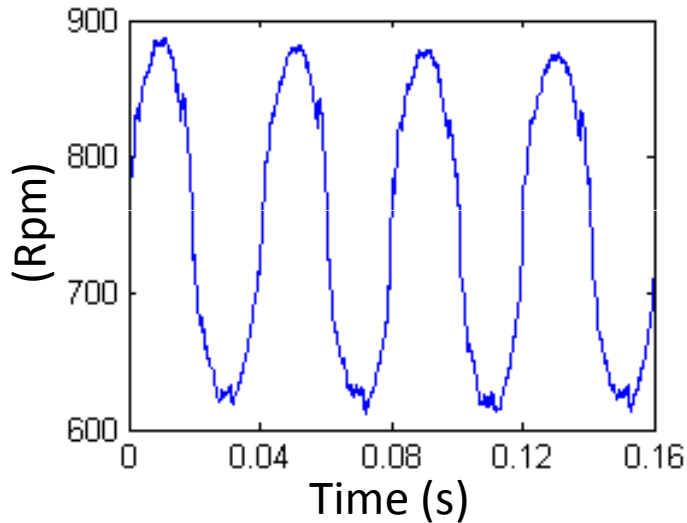
Housing vibration

Conclusion



Idle gear dynamics

Experimental and simulated relative velocities



$\Omega = 750$ rpm et $A = 100$ rpm
Neutral

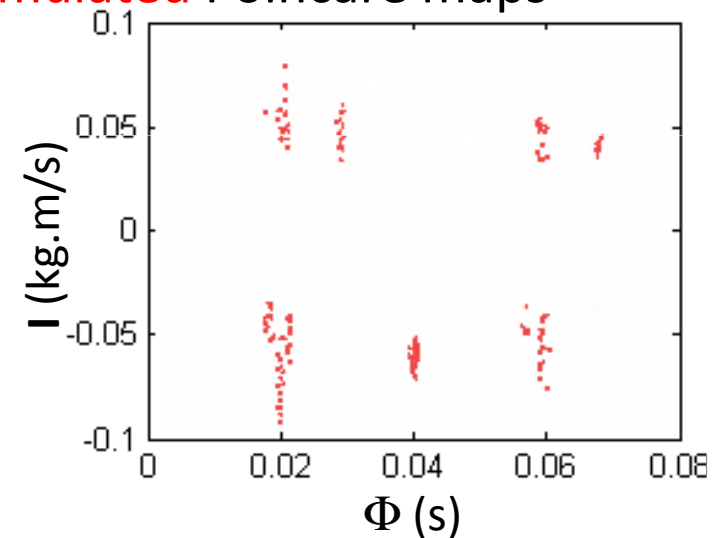
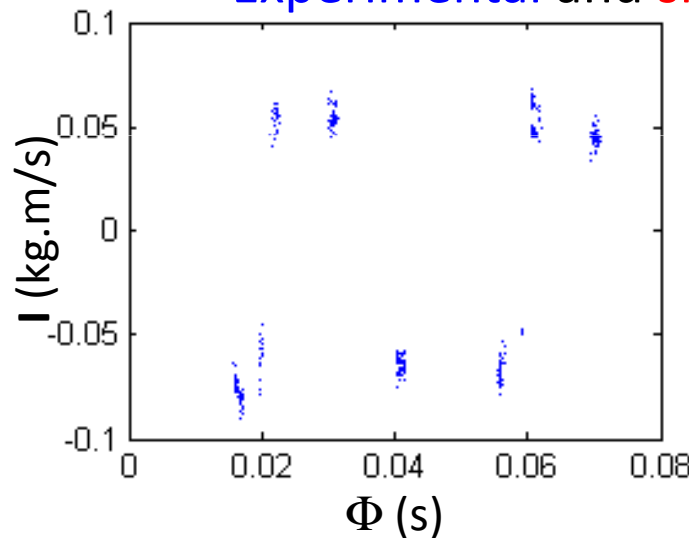
$$\Phi_i = t_i [T]$$

Φ : phase (s)

t_i : Impact time

T : period

Experimental and simulated Poincaré maps



Introduction

Numerical model

Idle gear dynamics

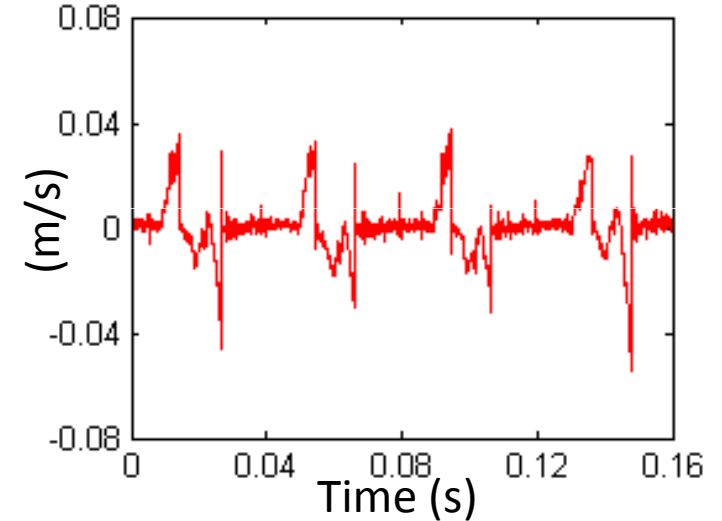
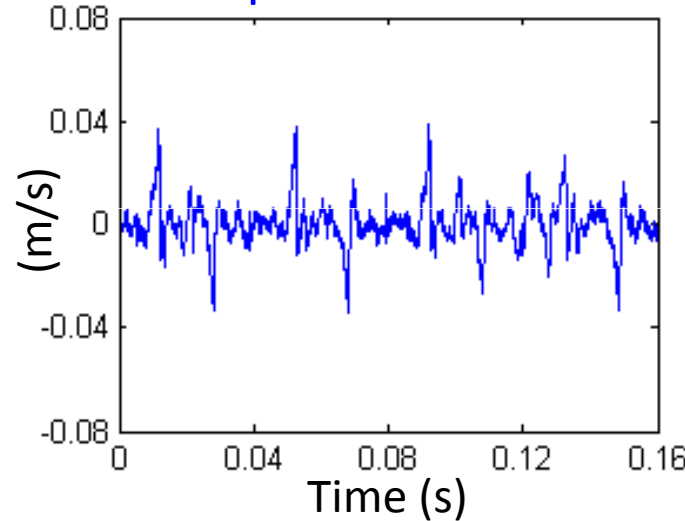
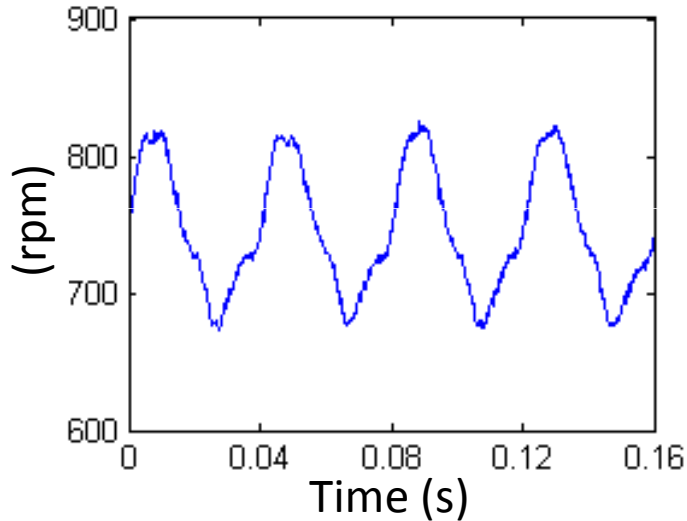
Housing vibration

Conclusion



Idle gear dynamics

Experimental and simulated relative velocities



$\Omega = 750$ rpm et $A = 125$ rpm
3rd ratio engaged

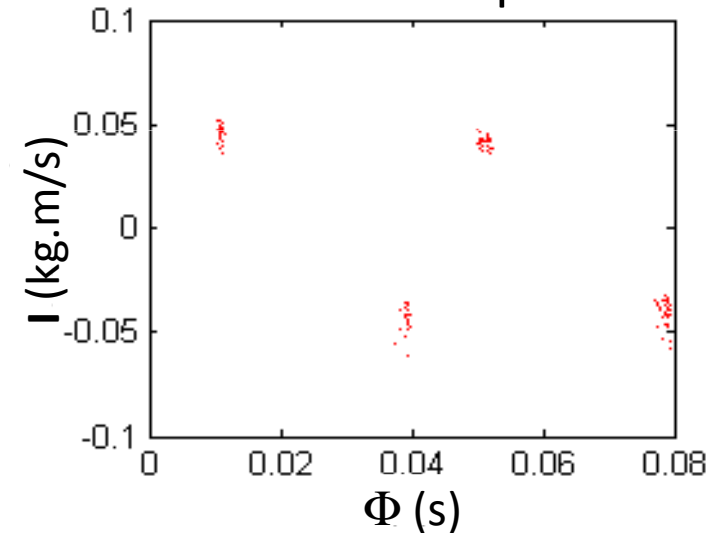
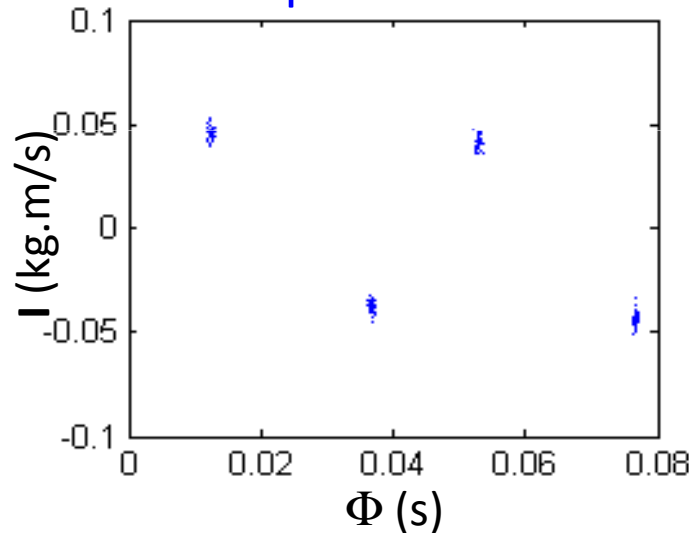
$$\Phi_i = t_i [T]$$

Φ : phase (s)

t_i : Impact time

T : period

Experimental and simulated Poincaré maps



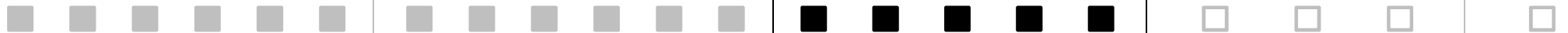
Introduction

Numerical model

Idle gear dynamics

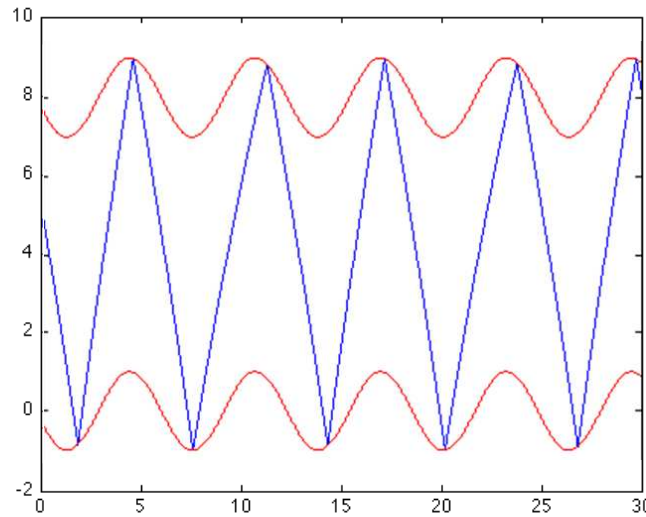
Housing vibration

Conclusion

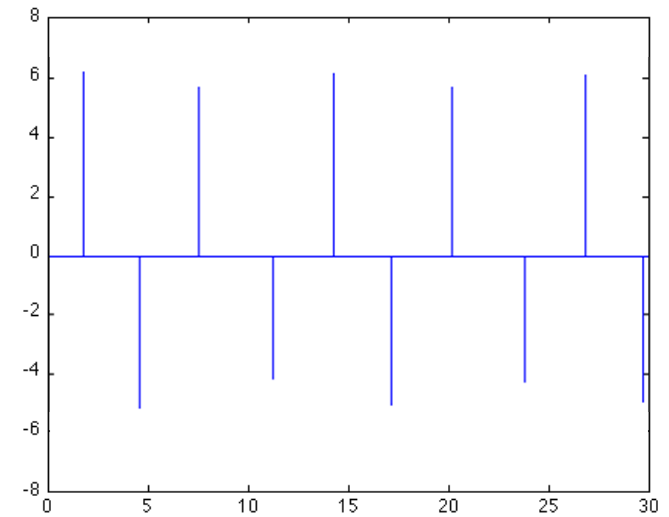


Housing vibration

Model outputs

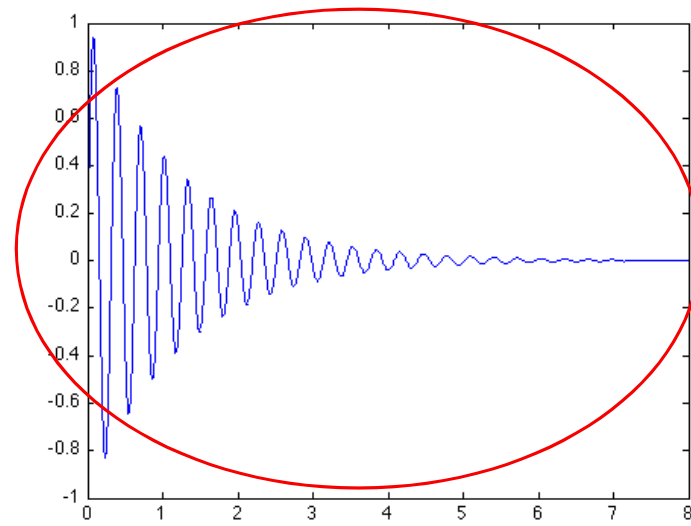


Time response

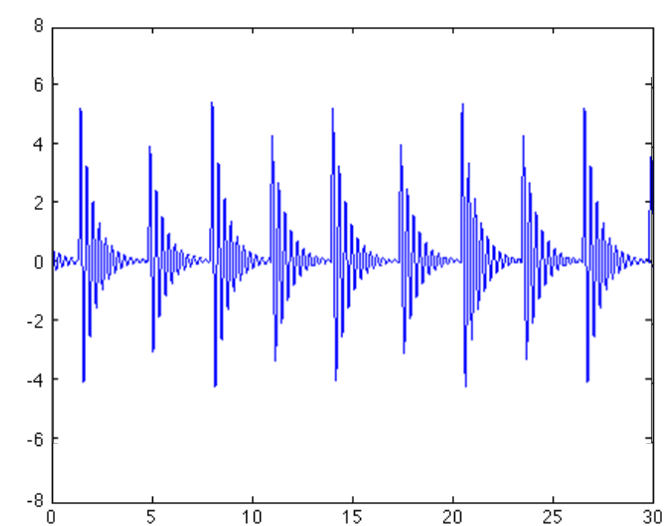


Successive impulses

Housing response



Measured transfer function



Housing response

Introduction



Numerical model



Idle gear dynamics



Housing vibration



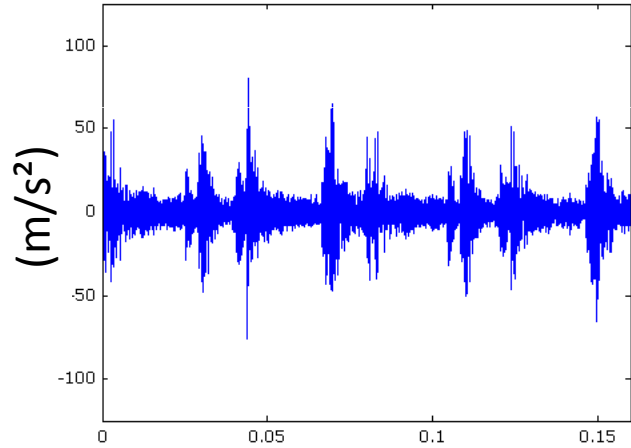
Conclusion



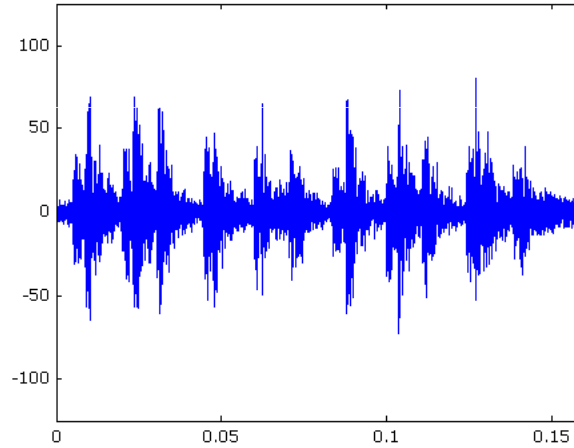
Housing vibration $\Omega=750$ rpm

Experiments

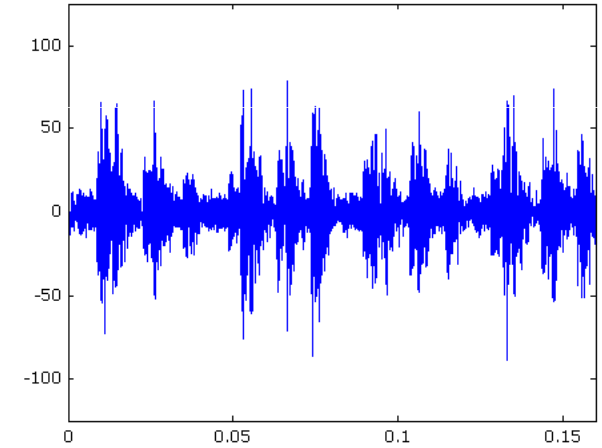
A=50 rpm



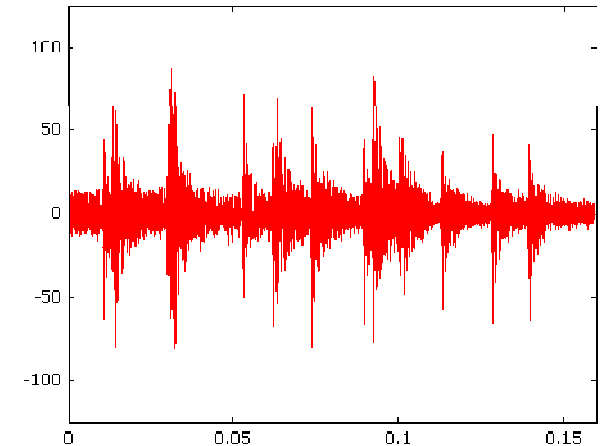
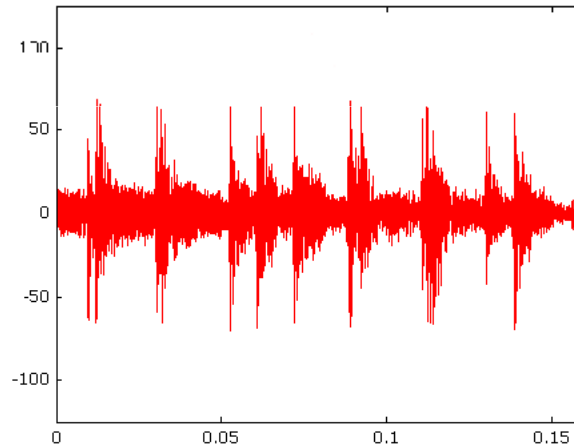
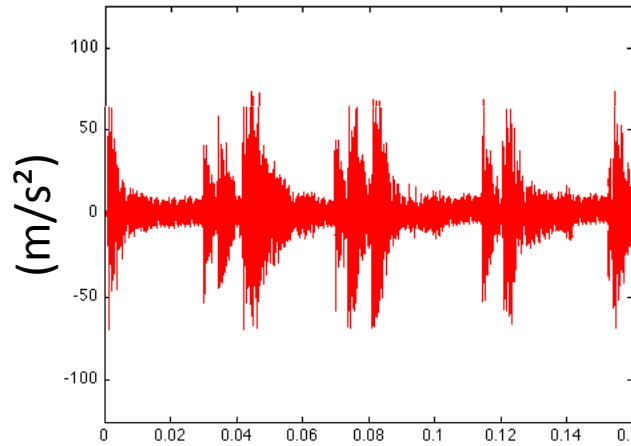
A=75 rpm



A=100 rpm



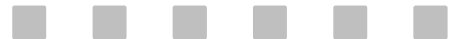
Simulation



Introduction



Numerical model



Idle gear dynamics



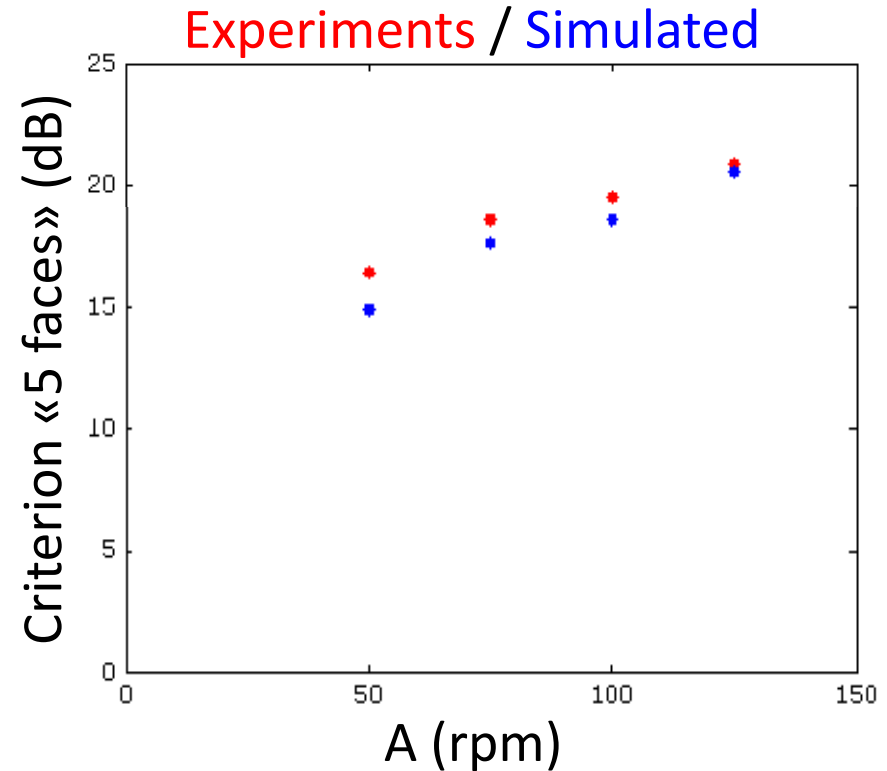
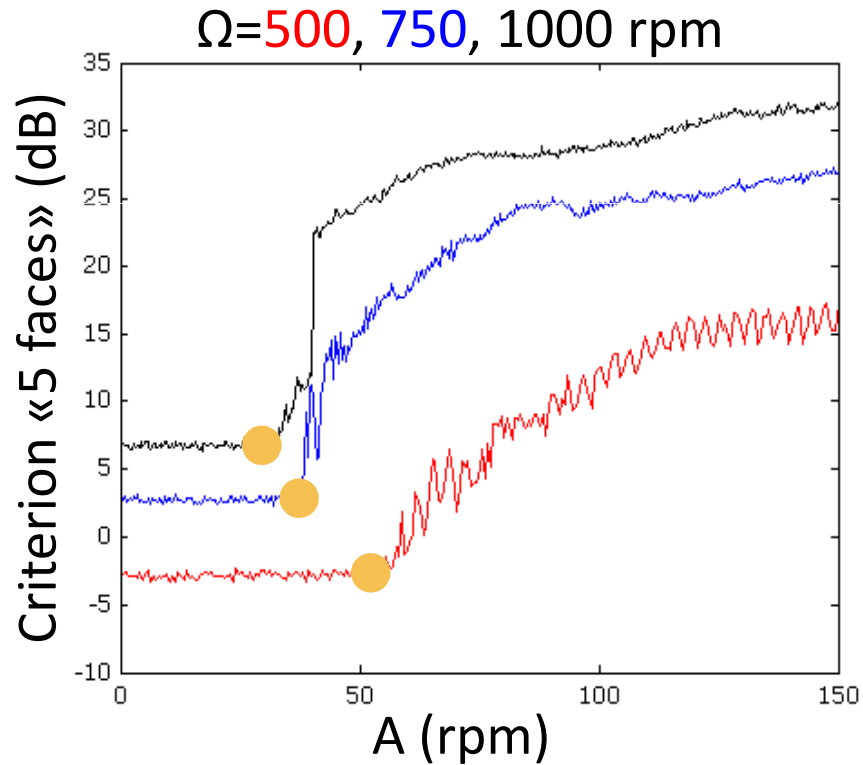
Housing vibration



Conclusion



Renault Criterion «5 faces»



A	50 rpm	75 rpm	100 rpm	125 rpm
Experiments	16,4 dB	18,6 dB	19,5 dB	20,9 dB
Simulation	14,9 dB	17,6 dB	18,6 dB	20,6 dB
Error	1,5 dB	1,0 dB	0,9 dB	0,3 dB

Introduction

Numerical model

Idle gear dynamics

Housing vibration

Conclusion



Conclusion

- Experiments performed with BACY allowed non linear numerical model.
- Operational software.
- Rattle noise can be predicted for:
 - any gearbox,
 - any gear ratio,
 - any operating conditions.
- Parametric studies allow gearbox design optimization.

